TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

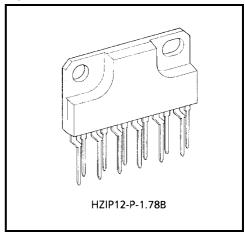
TA8429H

3.0A FULL BRIDGE DRIVER

The TA8429H is full bridge driver IC for brush motor rotation control that has current capability of up to $3.0~\mathrm{A}$ (AVE.). Thermal shutdown and short current protector are provided. And also stand–by function available.

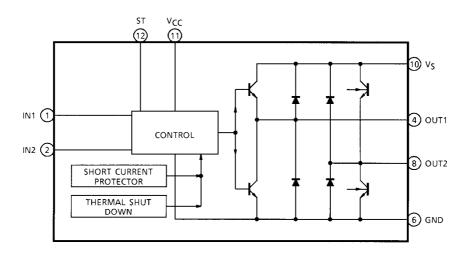
FEATURES

- Output current is as large as 3.0 A (AVE.) and 4.5 A (PEAK.)
- Stand-by mode available: IST \leq 100 μ A (MAX.)
- Thermal shutdown and short circuit protector circuit are provided.
- 4 modes (Forward / reverse / short brake and stop) are available with 2 low active TTL compatible inputs control.
- Free wheeling diodes are equipped.
- HZIP power package sealed.
- Wide range of operating voltage: $V_{CC} = 7 \sim 27 \text{ V}$ $V_{S \text{ (opr.)}} = 0 \sim 27 \text{ V}$



Weight : 4.04 g (Typ.)

BLOCK DIAGRAM



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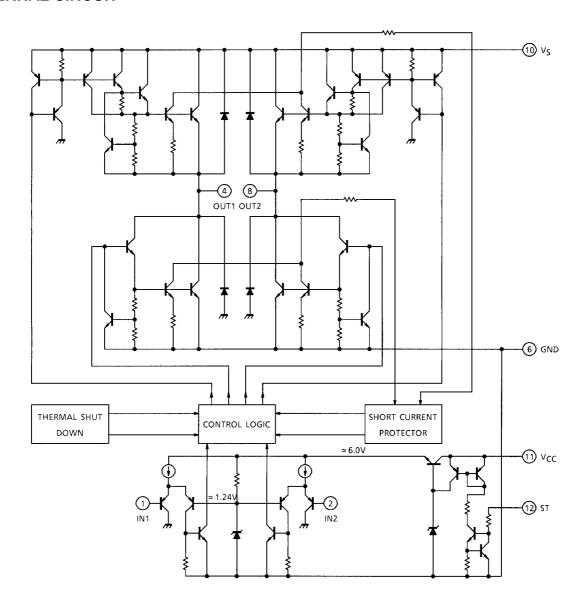
Note 1: Pin (3), (5), (7), and (9) are non connection.

Note 2: Heat fin is connected with GND with low impedance.

PIN FUNCTION

| PIN No. | SYMBOL | FUNCTIONAL DESCRIPTION | | | | |
|---------|-----------------|--|--|--|--|--|
| 1 | IN 1 | TL compatible control inputs | | | | |
| 2 | IN 2 | (PNP type low active comparator inputs) | | | | |
| 3 | N.C | Ion connection | | | | |
| 4 | OUT1 | Output terminals, free wheeling diodes are connected between each output with GND and V _S . | | | | |
| 5 | N.C | Non connection | | | | |
| 6 | GND | GND terminal | | | | |
| 7 | N.C | Non connection | | | | |
| 8 | OUT2 | Output terminals, free wheeling diodes are connected between each output with GND and V _S . | | | | |
| 9 | N.C | Non Connection | | | | |
| 10 | Vs | Supply voltage terminal for Motor Drive | | | | |
| 11 | V _{CC} | Supply voltage terminal for control circuit | | | | |
| 12 | ST | Stand-by terminal. Stand-by state is obtained with this terminal connected with GND (or Open). | | | | |

INTERNAL CIRCUIT



FUNCTION

| | INPUT | | OUT | PUT | MODE | |
|-----|-------|----|----------------------|------|-------------|--|
| IN1 | IN2 | ST | OUT1 | OUT2 | MOTOR | |
| Н | Н | Н | L | L | Short brake | |
| L | Н | Н | L | Н | CW / CCW | |
| Н | L | Н | Н | L | CCW / CW | |
| L | L | Н | OFF (high impedance) | | Stop | |
| H/L | H/L | L | OFF (high impedance) | | Stand-by | |

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MAXIMUM RATINGS (Ta = 25°C)

| CHARACTERISTIC | | SYMBOL | RATING | UNIT | |
|-----------------------|------|----------------------------------|----------------------|------|--|
| Supply Voltage | | V _{CC} , V _S | 30 | V | |
| Input Voltage | | V _{IN} | -0.3~V _{CC} | V | |
| Output Current | AVE. | I _{O (AVE.)} | 3.0 | Α | |
| Output Guirent | PEAK | I _{O (PEAK)} | 4.5 (Note 1) | | |
| Power Dissipation | | Po | 2.25 (Note 2) | W | |
| | | P _D | 21.6 (Note 3) | 1 ۷۷ | |
| Operating Temperature | | T _{opr} | -30~85 | °C | |
| Storage Temperature | | T _{stg} | -55~150 | °C | |

Note 1: t = 100 ms Note 2: No heat sink Note 3: Tc = 85°C

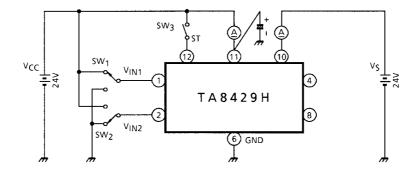
ELECTRICAL CHARACTERISTICS (V_{CC} = 24 V, V_S = 24 V, Ta = 25°C)

| CHARACTERISTIC | SYMBOL | TEST CIR- CUIT | TEST CONDITION | MIN | TYP. | MAX | UNIT | |
|---|-------------------|----------------------|-----------------------------------|-----|------|-----|------|--|
| | I _{CC1} | | Stop mode | _ | 6 | 12 | | |
| Quiescent Current (I) (V _{CC} Line) | I _{CC2} | 1 | Forward / reverse mode | _ | 20 | 40 | mA | |
| | I _{CC3} | | Brake mode | _ | 20 | 40 | | |
| | l _{S1} | Stop mode | _ | 3 | 8 | | | |
| Quiescent Current (II) (V _S Line) | I _{S2} | 1 | Forward / reverse mode | _ | 16 | 40 | mA | |
| , | I _{S3} | | Brake mode | _ | 3 | 8 | | |
| Input Voltage | V_{INL} | 2 | _ | _ | _ | 0.8 | V | |
| input voitage | V _{INH} |] | _ | 2.0 | _ | _ | | |
| Input Current | I _{INL} | - 2 | V _{IN} = GND | _ | _ | 12 | μΑ | |
| input Current | I _{INH} | | V _{IN} = V _{CC} | _ | _ | 10 | | |
| Output Saturation Voltage (Note) | V _{sat1} | - 3 | I _O = 1.5 A | _ | 2.1 | 2.8 | V | |
| Output Saturation Voltage (Note) | V _{sat2} | | I _O = 3.0 A | _ | 3.3 | 4.1 | | |
| Output Leakage Current | I _{LU} | 4 | V _L = 25 V | _ | _ | 50 | μА | |
| Output Leakage Current | ILL | | V _L = 25 V | _ | _ | 50 | | |
| Diode Forward Voltage | V _{FU} | - 5 | I _F = 3.0 A | _ | 5.0 | _ | V | |
| Diode Folward Voltage | V_{FL} | | I _F = 3.0 A | _ | 1.5 | _ | | |
| Limiting Current | I _{SD} | _ | _ | _ | 5 | _ | Α | |
| Thermal Shutdown Circuit Operating Temperature | T _{SD} | _ | _ | _ | 150 | _ | °C | |
| Stand-by Current | I _{ST} | 1 | _ | _ | _ | 100 | μA | |
| Propagation Dolay Time | t _{pLH} | 2 | _ | _ | 1 | 10 | μs | |
| Propagation Delay Time | t _{pHL} | 2 | _ | _ | 1 | 10 | | |

Note: Upper and lower side total

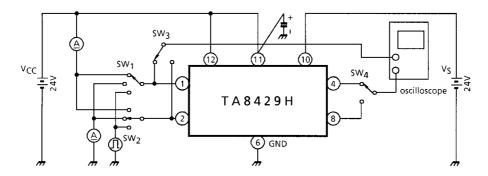
TEST CIRCUIT 1

IS1, IS2, IS3, ICC1, ICC2, ICC3, IST



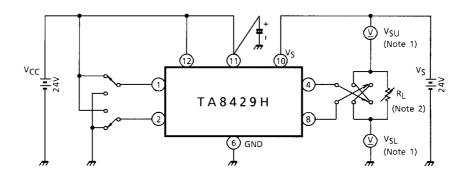
TEST CIRCUIT 2

 V_{INH} , V_{INL} , I_{INH} , I_{INL} , t_{pHL} , t_{pLH}



TEST CIRCUIT 3

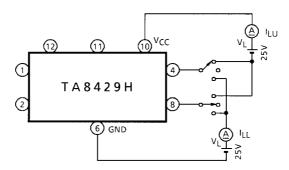
 V_{sat}



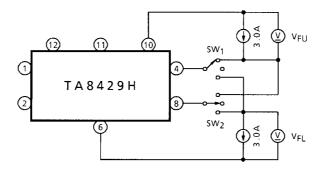
Note 1: V_{sat} = V_{SU} + V_{SL}

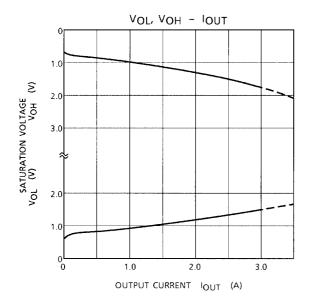
Note 2: Calibrate I_O to 1.5 / 3.0 A by R_L

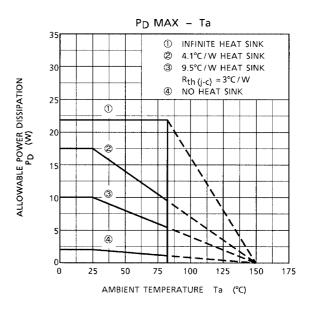
TEST CIRCUIT 4 I_{LU}, I_{LL}

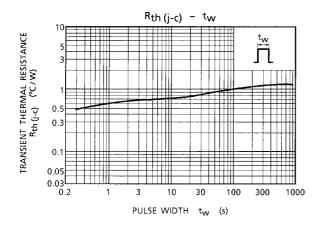


TEST CIRCUIT 5 V_{FU}, V_{FL}



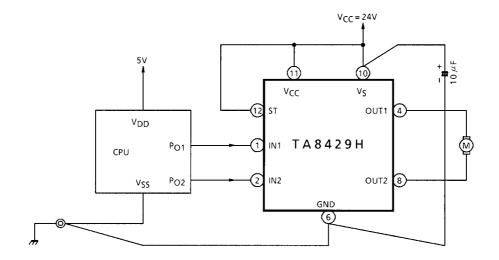




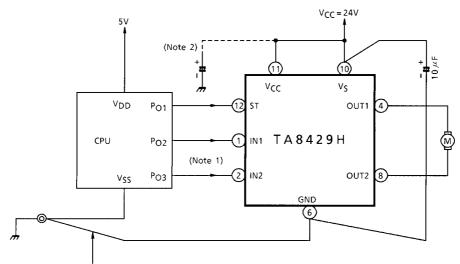


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APPLICATION CIRCUIT 1. (Single power supply operation)



APPLICATION CIRCUIT 2. (Dual power supply (Control and Motor) operation)

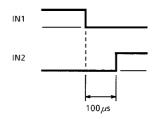


Not to have a common impedance with other lines and use low impedance wire.

Note 1: Recommend to take approximately 100 μs of input dead time for reliable operations.

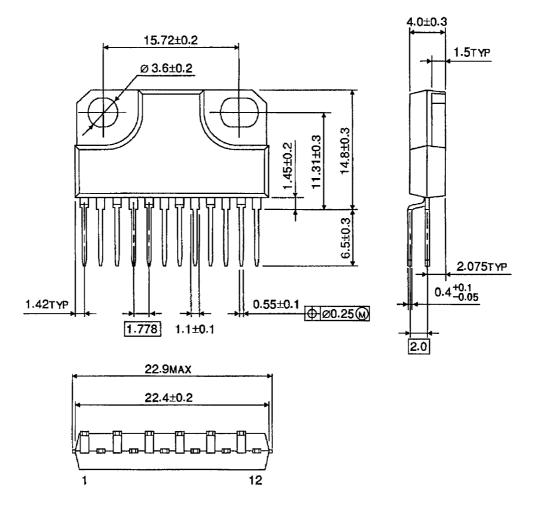
Note 2: Connect if required.

Note 3: Utmost care is necessary in the design of the output line, V_S and GND line since IC may be destroyed due to short–circuit between outputs, air contamination fault, or fault by improper grounding.



PACKAGE DIMENSIONS

HZIP12-P-1.78B Unit: mm



Weight: 4.04 g (Typ.)

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