

AD2XX Family for RS-232 Communications

by Matt Smith

The AD230–AD241 is a product line specifically designed for RS-232 communications applications. All parts in the product line meet or exceed the standard requirements and offer superior performance in many areas. The present RS-232 requirements include conformance to the EIA-232D standard, low power consumption, low cost, high reliability and operation from a single +5 V power supply.

The AD2XX family of interface products meets this need by integrating RS-232 drivers, RS-232 receivers and a charge pump voltage converter onto the same chip. CMOS technology is used to keep the power consumption to an absolute minimum. In addition, some members of the family feature a shutdown or sleep mode which can be used to disable the devices thereby reducing the power consumption even further.

The AD2XX family is designed to meet the EIA-232D specifications while operating from a single +5 V power supply. This is achieved by the use of an on-chip voltage doubler.

Older generation RS-232 drivers required three separate power supplies: +5 V, +12 V and –12 V. This resulted in large bulky power supply units. Linear voltage regulators tend to be inefficient and are wasteful of power. This is especially a problem in today's portable equipment which operates with battery powered supplies. Ideally a single power supply should be used which can easily be derived from a battery pack. Switch mode regulators can achieve this and are efficient in terms of useful power but again can be quite bulky, a serious drawback in portable equipment. In addition to this, switch mode supplies generate severe electrical noise which requires careful screening in order to conform to strict EMI regulations.

The AD2XX solves all these problems by operating from a single +5 V power supply. An on-chip charge pump voltage converter generates ± 10 V levels internally, thereby allowing the RS-232 output levels to be developed. The charge-pump technique is an extremely efficient method of stepping up the input voltage and is suitable for applications where the power requirements

are modest. It is therefore ideally suited to RS-232-type applications.

CHARGE PUMP OPERATION

The charge pump uses a switched, floating-capacitor technique to double and then invert the input +5 V supply. This generates voltages of +10 V and –10 V.

The voltage doubler schematic is shown in Figure 1, while the inverter is shown in Figure 2.

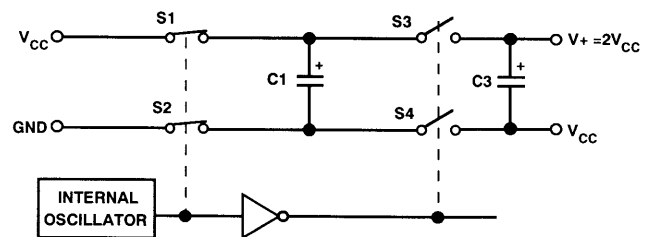


Figure 1. Voltage Doubler

The internal oscillator controls two phases of circuit operation.

During the first clock phase, switches S1 & S2 are closed causing capacitor C1 to charge up to V_{CC} (+5 V).

During the second phase, S1 & S2 are opened and S3 & S4 are closed. The negative terminal of C1 is connected to V_{CC} via S4. The voltage at V+ is therefore $V_{CC} + V_{CC} = 2V_{CC}$. Capacitor C3 acts as a reservoir capacitor to maintain the voltage at $2V_{CC}$ during clock phases when S3 & S4 are open. It should be noted that this reservoir capacitor is connected between V+ and V_{CC} for optimum performance.

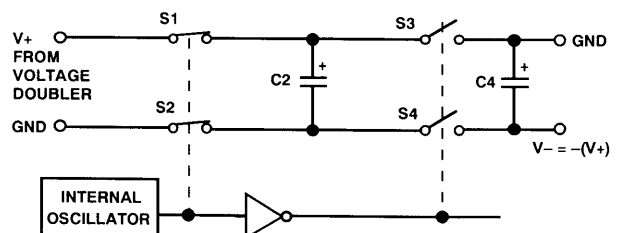


Figure 2. Voltage Inverter

The voltage at $V+$ is $2V_{CC}$ or $+10V$, and this is then used to generate $-10V$ using a similar technique to that already described. Again, during the first clock phase $S1$ & $S2$ are closed thereby charging $C2$ up to $10V$. During the second clock phase, $S1$ & $S2$ are opened and $S3$ & $S4$ are closed. The positive terminal of $C2$ is connected to GND via $S3$. This forces the potential at $V-$ to $-10V$. Again the output reservoir capacitor ($C4$ in this case) maintains the output voltage relatively constant for clock cycles when $S3$ & $S4$ are open.

In order to conserve board space, the values of capacitors $C1$ to $C4$ can be reduced. Reducing $C1$ & $C2$ results in higher output impedance on the $V+$ and $V-$ supplies, while reducing $C3$ & $C4$ causes increased ripple on the outputs. The increased output impedance & ripple is most noticeable at high temperatures, and if operation at extended temperatures is not required, then it is perfectly acceptable to reduce the component values.

The capacitors on the AD233 and the AD235 are integrated into the package, and so no external capacitors are required thereby reducing board space and saving on components.

Transmitter Outputs

The charge pump voltages ($\pm 10V$) are used internally to provide power for the RS-232 drivers. Under worst case conditions of high temperatures and maximum loading, the drivers are guaranteed to provide $\pm 5V$ levels on the RS-232 drivers. Typically the outputs provide $\pm 9V$ levels. This exceeds the minimum levels and permits operation well beyond the minimum RS-232 requirements.

Slew rate of each output is tightly controlled and is limited to less than $30V/\mu s$. This is achieved by internal slew limiting, and there is no need for external slew limiting capacitors as is the case with some bipolar designs.

Latch-Up Immunity

Because of the nature of the environment in which an RS-232 link may function, it is extremely important that the interface devices are capable of withstanding several forms of abuse. This can take the form of a user attempting to plug in the connector the "wrong way around." This can cause transmitter outputs from the peripheral device to become momentarily shorted to other transmitter outputs on the terminal. The transmitter outputs on the AD2XX product line are capable of withstanding shorting to $\pm 15V$ with the driver output at either polarity. This is the highest continuous voltage which can be present in an RS-232 link.

The parts must also be capable of withstanding signals applied even when power is removed. A peripheral device is often plugged into the terminal serial port before it is powered up. Again the AD2XX family contain internal protection to protect the device. In this case, the protection is on the receiver inputs and takes the form of passive resistive protection. Passive protection has the advantage that it continues to operate even when there are no power supplies to the device.

These protection schemes are also designed to protect the device if the interface cable is incorrectly wired. Due to the confusion which surrounds the RS-232 interface, this is an all-too-likely possibility. Some peripheral devices require signal crossing in the cable or connector, while others require a straight-through connection. This confusion is partly due to the fact that the initial specification applied to a terminal-to-modem interface. In practice the RS-232 port is used to communicate with a wide variety of peripheral devices and is not limited to modem interfaces.

Overvoltage Protection

The driver outputs are protected against damage by overvoltages greater than $\pm 15V$ on the outputs. This is achieved by internal series 300Ω resistors on each transmitter output. This resistor also ensures full compliance with the EIA specification which requires a minimum power-down resistance of 300Ω on each output. This resistor provides current limiting under fault conditions if a powered-up driver is inadvertently shorted to the powered-down driver.

If for any reason there is a requirement for even greater protection than is inherent in the device, then this may be applied externally. For protection against voltages in excess of $\pm 15V$ on the transmitter outputs, external series resistors may be used. A series 100Ω resistor will provide protection up to $\pm 20V$. This is the simplest scheme, but it causes a slight degradation of the output voltage swing due to the higher output impedance. This is not normally a problem as the output levels are well above the minimum RS-232 voltage level requirements.

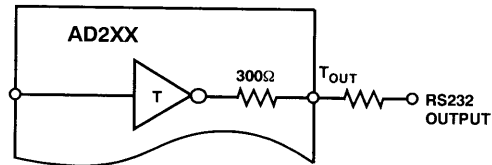


Figure 3. Resistor Protection to $\pm 20V$ for Transmitter Outputs

Another form of overvoltage protection uses TranZorbs.* These devices function as transient voltage suppressors and should be connected between the output and GND .

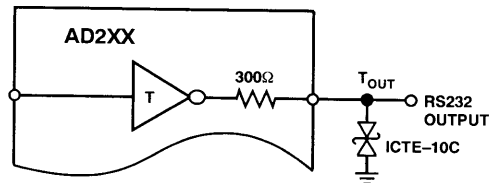


Figure 4. TranZorb Protection for Transmitter Outputs

*TranZorb is a registered trademark of General Semiconductor Industries, Inc.

As the outputs signal may swing either positive or negative, a bidirectional TranZorb should be used. This essentially contains two TranZorbs connected back to back. This scheme will provide voltage clamping at the TranZorb breakdown voltage for both positive and negative excursions. Effective spike suppression is also achieved due to the extremely fast TranZorb response time. A suitable TranZorb clamp rating for this application is ± 10 V. This protection scheme does not degrade the output voltage swing as the previous scheme did.

The receiver inputs must also be capable of withstanding excessive input signal voltages. The AD2XX family are protected against overvoltages of up to ± 30 V. This exceeds the RS-232 specification of ± 25 V. If even higher levels of protection are required, then this can be provided externally by TranZorbs. A suitable clamp rating for this application is ± 22 V.

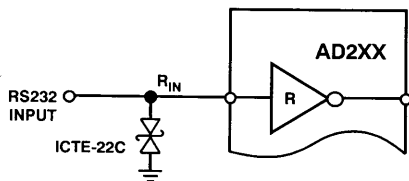


Figure 5. TranZorb Protection for Receiver Inputs

Noise Immunity

An RS-232 interface link is susceptible to noise pick up from the surrounding environment. The longer the link the more susceptible it becomes to outside interference. This is especially a problem in electrically hostile environments such as in a heavy industrial plant where large glitches can be injected or coupled onto the transmission line. These glitches can cause erroneous data reception by the RS-232 receiver. The AD2XX product line is designed to cope with noisy environments by the use of special on-chip filtering circuitry on the receiver inputs. These filters reject fast transient noise glitches up to 1 μ s in duration. In addition, further noise immunity is achieved by the use of Schmitt trigger inputs having 0.5 V of hysteresis. The result is a much improved data link offering superior reliability and error-free communication even with severe external noise.

Using an External +12 V Supply

If an external +12 V power supply is available in a system as well as +5 V, then the internal voltage doubler may be made redundant thereby saving two capacitors on the charge pump voltage doubler. The power requirements on the +5 V supply will also be reduced. If this scheme is used, then it is important that the correct power-up sequence be observed. The +12 V supply should be powered up before the +5 V supply. This is generally the case in non-PC systems where the +5 V supply is derived from the +12 V supply using a 7805 type regulator.

If this sequence cannot be guaranteed, then a general purpose diode (1N914 or equivalent) should be connected in series with the +12 V supply. This is illustrated in Figure 6. The purpose of the diode is to prevent cur-

rent backfeeding from V_{CC} and out the $V+$ line. Substantial fault-current could flow into a low impedance 12 V supply if this becomes a low impedance node when off. Under these conditions the diode will prevent the fault-current from flowing. Under normal conditions the diode is forward biased and has no effect.

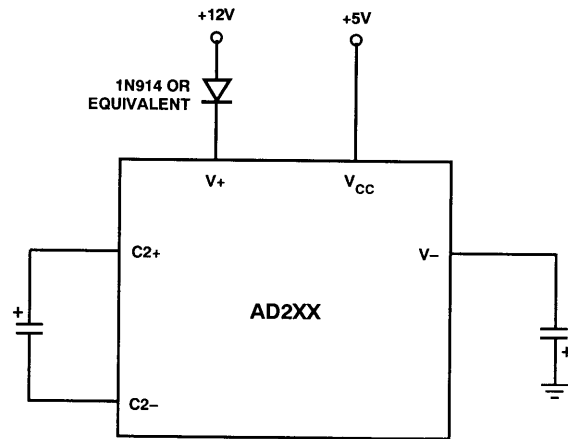


Figure 6. External +12 V Supply

Driving a Mouse

One of the most popular uses of a serial port on a personal computer is as a mouse interface. With the widespread acceptance of Windows,* a mouse has become an essential user interface tool. The older generation of mice interfaced to the PC using the serial communications port and generally required an external power supply to power the mouse hardware. The latest generation of mice use CMOS technology, and it is possible to power these devices directly from the communications port. In other words, the RS-232 transmitters should be capable of providing sufficient power to the mouse.

With a mouse connected, communication is in one direction only, i.e., from the mouse to the PC. Therefore the transmitter outputs on the serial port are not required for communication purposes. Instead, these are used as a power supply for the mouse. The mouse driver software sets up these transmitter outputs at permanently positive or negative levels as required by the mouse hardware. The transmitter outputs must therefore supply sufficient current drive to power the mouse. The power requirements are higher than those required by a standard RS-232 load. With the minimum RS-232 load, 3 k Ω , the driver must maintain ± 5 V levels giving a current drive of ± 2 mA.

In order to drive a mouse, however, greater current must be available. A typical mouse will require approximately 5 mA on a driver output. The AD2XX product line is designed to maintain ± 5 V output levels with a current drain of 5 mA on each driver output.

There is a considerable variation in power requirements between mice from different manufacturers, and some mice may require even greater current drive. This may

*Windows is a registered trademark of Microsoft Corp.

be achieved by connecting two transmitters in parallel thereby doubling the effective current available. However, with the vast majority of mice this will not be necessary.

TYPICAL APPLICATIONS

The AD230-AD241 family contain a variety of transmitter/receiver combinations which will satisfy all communications needs. Some of the products are general purpose devices which are suitable for a wide range of differing applications. Others contain the exact combination of drivers/receivers for a particular function. One of the simplest RS-232 communication links uses 5 signal lines and may be implemented using a single AD232 device. This is illustrated in Figure 7.

More complex interfacing schemes use a greater number of transmitters and receivers. A complete RS-232 implementation designates 22 signal lines. This includes secondary data channels as well as provision for synchronous transmission. This has led to a certain amount of confusion and incompatibility problems between RS-232 terminals.

In practice, most of these lines are redundant. As a result, the industry has formed a de facto "standard" using eight signal lines. This has been shown to be perfectly adequate for most communication needs. Most modern personal computers have adopted this standard and contain a pair of 9-pin serial ports rather than the 25-pin DB25 connector which can be found on older machines. These 9-pin serial ports contain 8 signal lines and a ground terminal. The signal lines are made up from three transmitters and five receivers. This forms a small subset of the original 22 signal lines. Only the

most important RS-232 signals are used. The signal designations and their functions are described below.

Pin No.	Function	Source	Abbreviation
1	Data Carrier Detect	DCE	DCD
2	Received Data	DCE	RXD
3	Transmitted Data	DTE	TXD
4	Data Terminal Ready	DTE	DTR
5	Signal Ground		
6	Data Set Ready	DCE	DSR
7	Request to Send	DTE	RTS
8	Clear to Send	DCE	CTS
9	Ring Indicator	DCE	RI

The function of each of these signal lines is as follows:

Function	Description
Transmitted Data	From the DTE to the DCE
Received Data	From the DCE to the DTE
Request to Send	A signal from the DTE to the DCE indicating that it wishes to transmit data
Clear to Send	A signal from the DCE, in response to a RTS, that it now can send the data
Data Set Ready	The DCE telling the DTE that it is connected to the telephone line
Data Terminal Ready	The DTE telling the DCE that it is ready to transmit or receive data
Data Carrier Detect	The DCE telling the DTE that it is receiving valid signals
Ring Indicator	The DCE telling the DTE that it has detected an incoming call
GND	Ground Reference

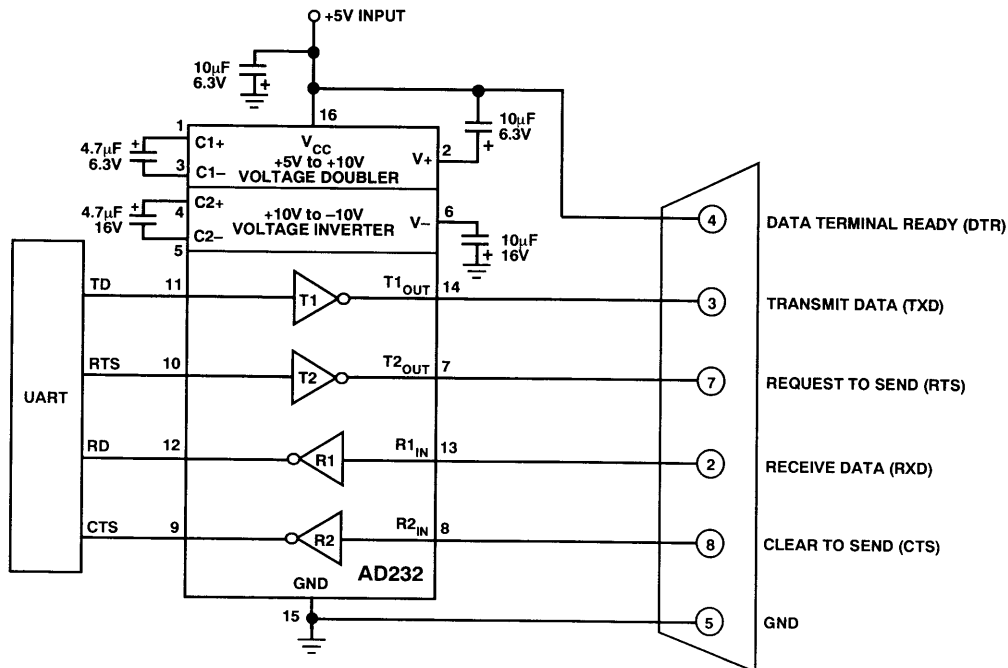


Figure 7. Minimum RS-232 Link Using the AD232

The AD241 is suitable for this 9-pin implementation as it contains sufficient drivers/receivers to meet the requirements in a single package. A typical application showing the AD241 is illustrated in Figure 8.

A typical communications sequence is as follows. The UART in the terminal (DTE) turns on the Request to Send (RTS) line. This signals the peripheral (DCE) that the terminal wishes to send data. The peripheral responds with a Clear to Send (CTS) signal. The terminal now starts transmitting data on its data (TXD) line. When transmission is complete, the terminal turns off the RTS line. In response to this, the peripheral turns off CTS and the link is terminated.

Figure 9 shows a different type of interface where a high resolution Analog to Digital Converter is interfaced to a personal computer using the RS-232 port. This circuit forms part of a remote data acquisition system. The remote ADC transmits serial data back to a personal

computer for analysis. In this case therefore, the ADC acts as the peripheral device. This interface differs from the previous examples in that it shows the RS-232 interface device located at the peripheral end of the link. There will of course be a similar RS-232 arrangement located at the PC end.

The ADC chosen is a high resolution converter featuring an asynchronous UART compatible interface. Operation of the interface is as follows. The DRDY output from the AD7701 ADC signals the terminal that the conversion is complete and data is ready. In response to this, the remote terminal activates the DTR line. This indicates that the terminal is ready and this line is used as a chip select for the AD7701. This initiates the data transfer. The data is then transmitted as two serial bytes in UART compatible format.

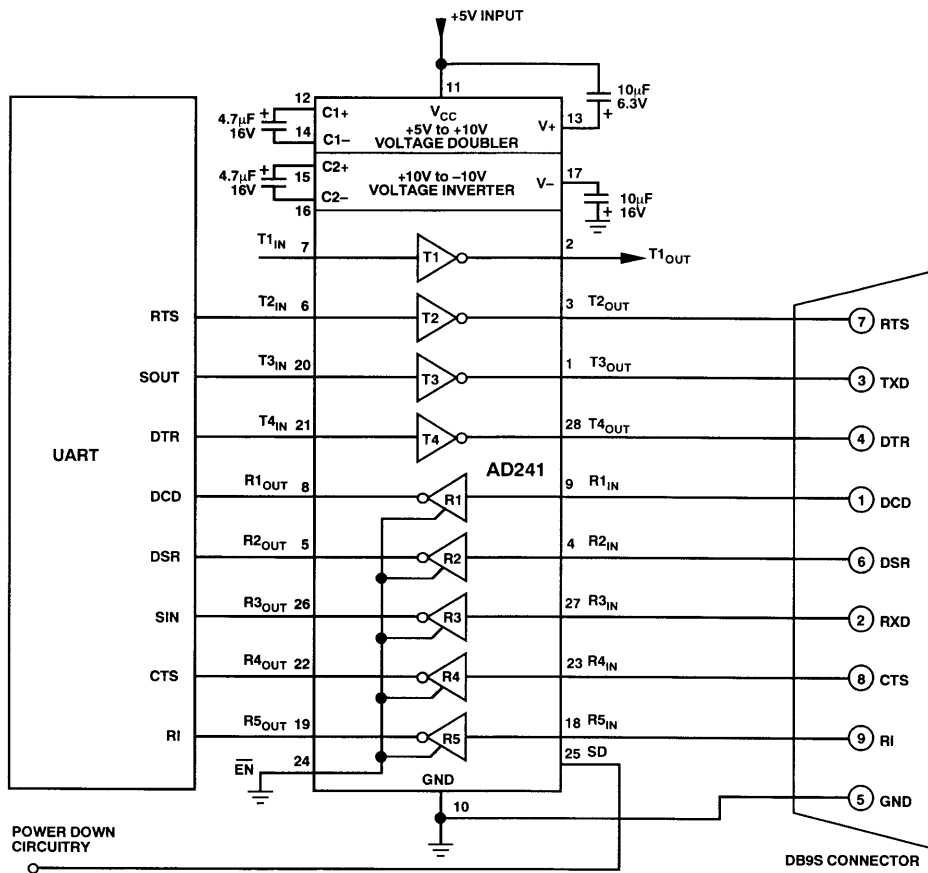


Figure 8. Complete RS-232 Link Using the AD241

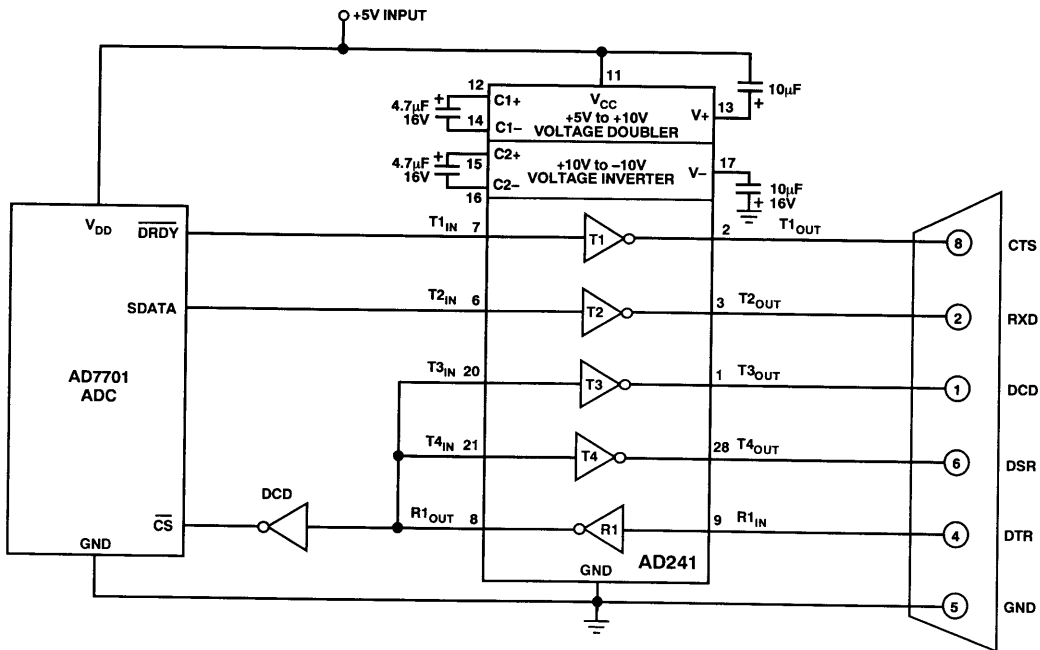


Figure 9. Remote Data Acquisition System Using the AD241 and AD7701

A simple Basic program to illustrate the data collection follows.

This program reads the input data from the serial port and displays the received binary data in HEX format on the screen. It assumes that the data is being received on COM1. The serial baud rate is set at 1200 in line 20. The next line defines a text string which sets up the data format and control line status of the COM1 serial port. The text string is then used to open a data buffer for the port into which two bytes are read. The data is read in two 8-bit bytes and these are then concatenated to form a single 16-bit result which is converted into HEX format. This is then printed on the screen. The serial port is then terminated by closing the data buffer. Note that the buffer must be opened and closed in order that the serial port control lines follow the correct sequence. The program loops back to the start and the reading sequence is repeated continuously.

For more information on the interface and on the AD7701 Analog to Digital Converter, the reader is referred to an application note "Evaluation Board for the AD7701/AD7703 Sigma Delta A/D Converter" published by Analog Devices, publication number E1483-15-1 2/90.

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10 CLS
20 BR$ = "1200"
30 COMFIL$ = "COM1 : "+BR$+" , N, 8, 2, RS, CS, DS, CD"
40 OPEN COMFIL$AS#1
50 FIELD 1, 2 AS D$
60 GET #1, 2
70 A$ = HEX$(ASC ( MID$( D$, 1, 1)))
80 B$ = HEX$(ASC ( MID$( D$, 2, 1)))
90 IF LEN (A$) = 1 THEN A$ = "0" + A$
100 IF LEN (B$) = 1 THEN B$ = "0" + B$
110 Y$ = A$ + B$
120 LOCATE 12, 20 : PRINT Y$
130 CLOSE #1
140 GOTO 40
150 END

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